Dyuman Aditya

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Education

Ecole Centrale de Nantes

 $MSc\ in\ Advanced\ Robotics$

• M1 (GPA 3.78/4.0): Artificial Intelligence, Control, Optimization, Computer Vision, Mobile Robots, Signal Processing, Modelling & Design of Manipulators

Sri Aurobindo International Centre of Education

BSc in Computer Science, Best Student Award

• Computer Science, Mathematics, Mathematical Statistics, Physics, Numerical Analysis, English Literature, Tamil

PUBLICATIONS

- Mukherji, K., Parkar, D., Pokala, L., Aditya, Dyuman, Shakarian, P. "Scalable Semantic Non-Markovian Simulation Proxy for Reinforcement Learning". In IEEE ICSC. (link)
- Bavikadi, D., Aditya, Dyuman, Parkar, D., Bavikadi, D., Shakarian, P., Mueller, G., Parvis, C., Simari, G. "Geospatial Trajectory Generation via Efficient Abduction: Deployment for Independent Testing". In ICLP. (link)
- Aditya, Dyuman, Mukherji, K., Balasubramanian, S., Chaudhary, A., Shakarian, P. (2023). "PyReason: Software for Open World Temporal Logic". In AAAI Spring Symposium. (link)

MANUSCRIPTS IN PREPERATION

• Mukherji, K., Aditya, Dyuman, Patil, J., Bavikadi, D., Shakarian, P. "Lower Lattice Annotated Logic for Open World Temporal Reasoning". Will submit to IJCAI 2025

EXPERIENCE

July. 2024 - Present **Researcher at Technical University of Darmstadt** Prof. Jan Peter's lab Darmstadt, Germany • Developed a navigation software stack for the MAB quadruped startup • Integrating legged kinematics into Visual Odometry for robust localization. Targeting IROS 2025 Mar. 2022 - Present **Research Assistant at Arizona State University** Prof. Paulo Shakarian's lab Tempe, Arizona USA • Developed an implementation for PyReason - an explainable inference software supporting annotated, real-valued, graph-based, and temporal logic • First Authored a manuscript presenting PyReason and experimental results published at AAAI-MAKE 2023 • Currently working on multiple research projects in the field of logic and reinforcement learning **Research Assistant at University of Maryland** June. 2023 - Present ARLIS College Park, Maryland USA • Developed a method to evaluate operational workflows due to added AI technology using PyReason as a simulator of the workflow **Research Intern at Carnegie Mellon University** Jun. 2022 - Nov. 2022 Pittsburgh, Pennsylvania USA Prof. Min Xu's lab • Evaluated performance for algorithms that find the position and orientation of particles on biomedical images • Started making improvements to the computer vision algorithms **Robotics & Machine Learning Research Intern** Jul. 2020 - Aug. 2022 Telekinesis AI Darmstadt, Germany Research

- Built a PyTorch Reinforcement Learning toolbox with 4 state-of-the-art algorithms from scratch and conducted experiments on OpenAI Gym
- Built custom reinforcement learning environments in Pybullet Drilling and Bin-picking. Conducted experiments on these using the reinforcement learning toolkit
- Developed a real-time, single object 6D object pose estimation pipeline and conducted experiments on the YCB dataset

Pondicherry, India October 2022

Nantes, France September 2025

Industrial

- Developed a package to enable real-time motion control from external PCs
- Assisted in porting a large-scale legacy robotic application from Python to C++
- Designed and manufactured a hand-mounted device to track the orientation of the operator's hand
- Developed a networking package for TCP/IP and UDP communications between software components and industrial robots
- Developed a 3D Unity environment to display robots and integrated it into the main Telekinesis software

PATENTS AND PATENT APPLICATIONS

Controlling Industrial Machines by Tracking Movements of their Operators (*link*)Patent Pending Inventors: Pal, S., Chakraborty, K., Aditya, Dyuman, Datta, A., Peters, J.

ONLINE CERTIFICATES

Deep Learning Specialization - with Andrew Ng Coursera (verification link)

Honours & Awards

Sri Aurobindo International Centre of Education

- Graduated with the **The best student award**: 2022. Awarded to the best student in the graduating class
- 9 Time Recipient of the Prize for Academic Excellence : 2011, 2014, 2015, 2016, 2017, 2019, 2020, 2021, 2022

Projects

Animatronic Hand

Designed and 3D printed an Animatronic hand that imitates an operator wearing a glove. Built a novel flex sensor using cheap potentiometers to measure finger movement. Presented in the annual school Science Fair

Low-Cost 3D Printer (link)

Designed, prototyped and built a high-resolution, low-cost 3D printer from scratch, with a novel screw based motion system. The project has received over 110K views on instructables.com (Won 2nd prize). Presented in the annual school Science Fair

EXTRA-CURRICULAR ACTIVITIES

Teaching & Mentoring

 $Sri\ Aurobindo\ International\ Centre\ of\ Education$

- Mentored freshmen in Mathematics (2022)
- Gave talks to high school students about my research and AI in general (2021-2022)
- Helped organize the annual science fair and mentored junior students (2019)
- Formed the "Science Group": a group of students interested in science and discussed breakthroughs and research papers in physics, chemistry, math and technology (2018)

Skills

Languages: English, French, Sanskrit, Tamil

Programming Languages: Python, C, C++, Matlab, Bash

Computer & Software Skills: Autodesk Fusion 360, Git, Linux, OpenAI Gym, LATEX

Libraries & Frameworks: PyTorch, Keras, OpenCV, ROS, Numpy, Eigen, Matplotlib, Pandas, Pybullet, PCL, Numba Soft Skills: Logical Reasoning, Written Communication, Verbal Communication, Time Management, Discipline, Eye for Detail, Self-motivation, Teamwork

Jan. 2018 - Dec. 2018

Jan. 2019 - Oct. 2019

Jun. 2020 - Oct. 2020